

CONTROLLED OBJECT EXTERNAL FORCE - PRIOR ART ELECTROMAGNET COMPENSATOR POWER AMP Fig. 1 ന TARGET VALUE Xo DISPLACEMENT SENSOR

¹/₁₁



TO ELECTROMAGNET 4 Fig. 2 - PRIOR HRT 3-3 3-2 DRIVE **S**2 CONTROL 3-1 ന INPUT SIGNAL FROM S1 COMPENSATOR 2

3-4



3-3 Fig. 3 - PRIOR ART 3-2 四· 83 3-1-5 PWM DEVICE (COMPARATOR) 3-4 3 - 1 - 6PWM CARRIER SIGNAL GENERATOR \$2 84 GAIN AMP 3 - 1 - 4SIGNAL REGULATOR 3-1-3 SIGNAL REGULATOR 3-1-1 3 - 1 - 2 -3-1A 3-1 S1 INPUT SIGNAL





